# 24LC01/24AA01 1K

# bits (128×8)Features

- Compatible with all I<sup>2</sup>C bidirectional data transfer • protocol
- Memory array: .
  - 1 Kbits (256bytes) of EEPROM
  - Page size: 16 bytes
- Single supply voltage and high speed:
- 1MHz
  - Random and sequential Read modes
- Write:
  - Byte Write within 3 ms
  - Page Write within 3 ms
  - Partial Page Writes Allowed

# Description

• The24LC01/24AA01 provides 2048 bits of serial • The device is optimized for use in many industrial and electrically erasable and programmable read-only memory (EEPROM), organized as 256 words of 8 bits each.

# **Pin Configuration**

8 -lead PDIP 8 -lead SOP 8 -lead TSSOP 0 0 VCC VCC A0 A0 8 A0 8 ₩P A1 2 ₩P A1 A1 2 7 7 7 2 A2 SCL A2 3 SCL A2 6 3 6 6 3 GND GND SDA GND SDA 5 4 5 4 5 8 -pad DFN 5-lead TSOT23-5 5-lead SOT23-5 WP VCC WP VCC 0 vcc 5 A0 8 4 5 4 1 2 7 WP A1 3 6 SCL A2 4 3 5 SDA GN⊅

SCL

GND

SDA

SCL

GND

SDA

# **Examples**

| 췵号                 | 封談      | 私印          | 工作电压    | 兼容电压 |
|--------------------|---------|-------------|---------|------|
| 24LC01B-I/P-TUDI   | DIP8    | 24LC01B-I/P | 1.8-5.5 |      |
| 24LC01BT-I/SN-TUDI | SOP8    | 24LC01BI/SN | 1.8-5.5 |      |
| 24LC01BT-I/ST-TUDI | TSSOP8  | 24LC01B     | 1.8-5.5 |      |
| 24LC01BT-I/OT-TUDI | S0T23-5 | M1QU        | 1.8-5.5 |      |
| 24AA01T-I/SN-TUDI  | SOP8    | 24AA01I/SN  | 1.8-5.5 | 1.7V |
| 24AA01T-I/ST-TUDI  | TSSOP8  | 24AA01      | 1.8-5.5 | 1.7V |
| 24AA01T-I/OT-TUDI  | S0T23-5 | B1QA        | 1.8-5.5 | 1.7V |

- Write Protect Pin for Hardware Data Protection
- Schmitt Trigger, Filtered Inputs for Noise • Suppression
- High-reliability
- Endurance: 1 Million Write Cycles - Data Retention: 100 Years
- Enhanced ESD/Latch-up protection – HBM 6000V

voltage operation are essential.

- 8-lead PDIP/SOP/TSSOP/ UDFN/TSOT23-5 and SOT23-5 packages
- commercial applications where low-power and low-

VCC

₩P

SCL

SDA





# **Pin Descriptions**

| Pin Name | Туре | Functions          |
|----------|------|--------------------|
| A0-A2    | I    | Address Inputs     |
| SDA      | I/O  | Serial Data        |
| SCL      | I    | Serial Clock Input |
| WP       | I    | Write Protect      |
| GND      | Р    | Ground             |
| Vcc      | Р    | Power Supply       |

Table 1

# **Block Diagram**

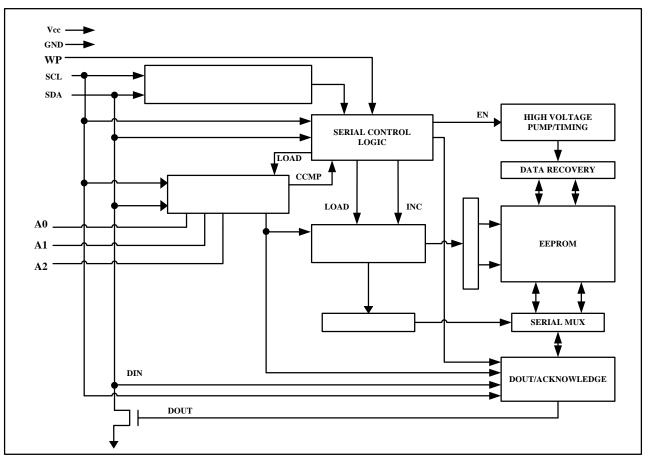


Figure 1

DEVICE/PAGE ADDRESSES (A2, A1 and A0): The A2, A1 and A0 pins are device address inputs that are hard wire for the 24LC01/24AA01. Eight 2K devices may be addressed on a single bus system (device addressing is discussed in detail under the Device Addressing section).

SERIAL DATA (SDA): The SDA pin is bi-directional for serial data transfer. This pin is open-drain driven and may be wire-ORed with any number of other open-drain or open- collector devices.

SERIAL CLOCK (SCL): The SCL input is used to positive edge clock data into each EEPROM device and negative edge clock data out of each device.

WRITE PROTECT (WP): The 24LC01/24AA01 has a Write Protect pin that provides hardware data protection. The Write Protect pin allows normal read/write operations when connected to ground (GND). When the Write Protection pin is connected to Vcc,

the write protection feature is enabled and operates as shown in the following Table 2.

| WP Pin Status | 24LC01/24AA01                |  |  |  |  |
|---------------|------------------------------|--|--|--|--|
| At VCC        | Full(2K) Array               |  |  |  |  |
| At GND        | Normal Read/Write Operations |  |  |  |  |

Table 2

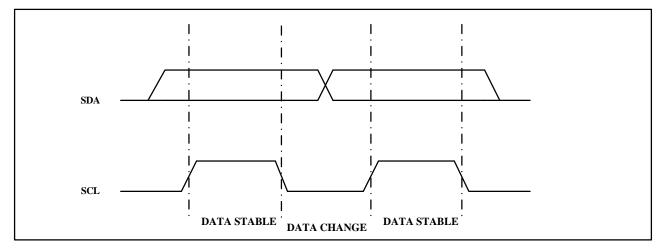
# **Functional Description**

# 1. Memory Organization

24LC01/24AA01, 2K SERIAL EEPROM: Internally organized with 16 pages of 16 bytes each, the 2K requires a 8-bit data word address for random word addressing.

# 2. Device Operation

CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see **Figure 2**). Data changes during SCL high periods will indicate a start or stop condition as defined below.



#### Figure 2. Data Validity

START CONDITION: A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see **Figure 3**).

STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see **Figure 3**).

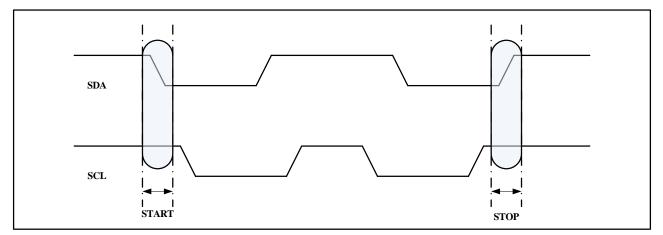
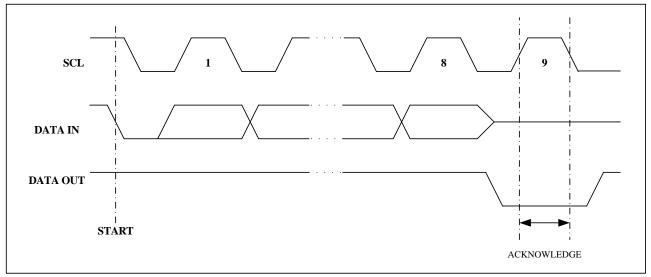


Figure 3. Start and Stop Definition



ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.



#### Figure 4. Output Acknowledge

STANDBY MODE: The 24LC01/24AA01 features a low-power standby mode which is enabled: (a) upon power-up and (b) after the receipt of the STOP bit and the completion of any internal operations.

MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

- 1. Clock up to 9 cycles.
- 2. Lock SDA high in each cycle while SCL is high.
- 3. Create a start condition.



# 3. Device Addressing

The 2K EEPROM devices all require an 8-bit device address word following a start condition to enable the chip for a read or write operation (see Figure 5)

| MSB |   |   |   |    |    |    | LSB |
|-----|---|---|---|----|----|----|-----|
| 1   | 0 | 1 | 0 | A2 | A1 | A0 | R/W |

# Figure 5. Device Address

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits as shown. This is common to all the Serial EEPROM devices.

The 2K EEPROM uses A2, A1 and A0 device address bits to allow as much as eight devices on the same bus. These 3 bits must be compared to their corresponding hardwired input pins. The A2, A1 and A0 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are allowed to float.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a "0". If a compare is not made, the chip will return to a standby state.

DATA SECURITY: The 24LC01/24AA01 has a hardware data protection scheme that allows the user to

write

protect the entire memory when the WP pin is at VCC.

**4** Write Operations BYTE WRITE: A write operation requires an 8-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the EEPROM will again respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, tWR, to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see Figure 7).

Figure 6. ADDRESS

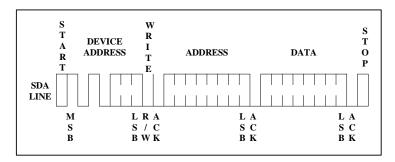
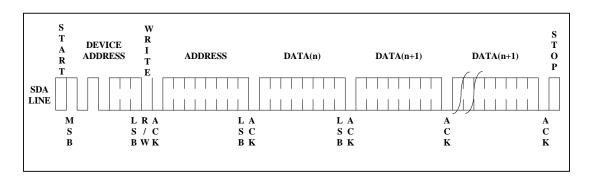


Figure 7. Byte Write



PAGE WRITE: The 2K EEPROM is capable of a 16-byte page write. A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to fifteen more data words. The EEPROM will respond with a "0" after each data word received. The microcontroller must terminate the page write sequence with a stop condition (see **Figure 8**).



### Figure 8. Page Write

The data word address lower four bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than sixteen data words are transmitted to the EEPROM, the data word address will "roll over" and previous data will be overwritten.

ACKNOWLEDGE POLLING: Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write sequence to continue.



# 5. Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page. The address "roll over" during write is from the last byte of the current page to the first byte of the same page. Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 9).

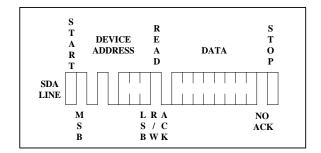


Figure 9. Current Address Read

RANDOM READ: A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see **Figure 10**)

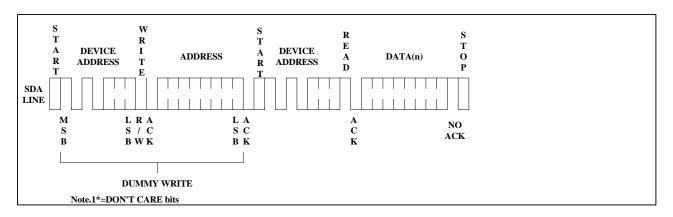


Figure 10. Random Read



SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see **Figure 11**).

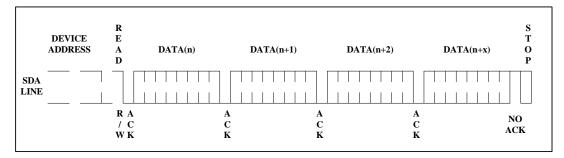


Figure 11. Sequential Read



# **Electrical Characteristics**

Absolute Maximum Stress Ratings:

|   | DC Supply Voltage                      |        |
|---|--|--------|
| • | Storage Temperature65°C to             | +150°C |
| • | Electrostatic pulse (Human Body model) | .6000V |

#### Comments:

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

# **DC Electrical Characteristics**

| 24LC01/24AA01                        | T <sub>A</sub> =-40°C to +85°C  |                  |         | V <sub>CC</sub> = +1.7V to +5.5V@400kHz<br>V <sub>CC</sub> = +2.5V to +5.5V@1MHz |         |      |                  |  |
|--------------------------------------|---------------------------------|------------------|---------|--|---------|------|------------------|--|
| 24LC01/24AA01 E1                     | T <sub>A</sub> =-40°C to +105°C |                  |         |  |         |      |                  |  |
| 24LC01/24AA01 E0                     | T <sub>A</sub> =-               | -40°C to +125°   | С       | C∟=100 pF  |         |      |                  |  |
| Parameter                            | arameter Symbol Min             |                  |         | Тур  | Max     | Unit | Condition        |  |
| Supply Voltage                       |                                 | Vcc1             | 1.7     | -  | 5.5     | V    | @400kHz          |  |
| Supply Voltage                       |                                 | Vcc2             | 2.5     | -  | 5.5     | V    | @1MHz            |  |
| Supply Current Vcc=5.0V              |                                 | IR               | -       | 0.14   | 0.3     | mA   | READ @ 400kHz    |  |
| Supply Current Vcc=5.0V              |                                 | lw               | -       | 0.28   | 0.5     | mA   | WRITE @ 400kHz   |  |
| Supply Current Vcc=5.0V              |                                 | ISB              | -       | 0.03   | 0.5     | μA   | VIN=VCC or VSS   |  |
| Input Leakage Current                |                                 | ILI              | -       | 0.10   | 1.0     | μA   | VIN=VCC or VSS   |  |
| Output Leakage Current               |                                 | Ilo              | -       | 0.05   | 1.0     | μA   | Vout=Vcc or Vss  |  |
| Input Low Level                      |                                 | VIL              | -0.3    | -  | Vcc×0.3 | V    | Vcc=1.7V to 5.5V |  |
| Input High Level                     |                                 | Vін              | Vcc×0.7 | 7 -  | Vcc+0.3 | V    | Vcc=1.7V to 5.5V |  |
| Output Low Level V <sub>CC</sub> =1. | 7V                              | V <sub>OL1</sub> | -       | -  | 0.2     | V    | IoL=0.15mA       |  |
| Output Low Level Vcc=5.              | 0V                              | V <sub>OL2</sub> | -       | -  | 0.4     | V    | IoL=3.0mA        |  |

#### Table 3

# **Pin Capacitance**

Applicable over recommended operating range from  $T_A = 25^{\circ}C$ ,  $f_{SCL} = 1.0$  MHz,  $V_{CC} = +2.5V$ 

| Parameter                       | Symbol | Min | Тур | Max | Unit | Condition           |
|---------------------------------|--------|-----|-----|-----|------|---------------------|
| Input/Output Capacitance(SDA)   | CI/O   | -   | -   | 8   | pF   | V <sub>IO</sub> =0V |
| Input Capacitance(A0,A1,A2,SCL) | CIN    | -   | -   | 6   | pF   | V <sub>IN</sub> =0V |

Table 4



# **AC Electrical Characteristics**

Applicable over recommended operating range from (unless otherwise noted):

| T <sub>A</sub> =-40°C to +85°C  |   | Vcc = +1.7V to +5.5V@400kHz  |  |  |  |
|---------------------------------|---|--|--|--|--|
| T <sub>A</sub> =-40°C to +105°C | $V_{CC} = +2.5V$ to $+5.5V@1MHz$  |  |  |  |  |
| T <sub>A</sub> =-40°C to +125°C | -   | C∟=100 pF  |  |  |  |
| Symbol                          | Mir   | ٦.   | Max.   | Units  |  |
| fscl                            | -   |  | 1000   | kHz  |  |
| t∟ow                            | 0.8   | 5  | -  | μs   |  |
| t <sub>ніGн</sub>               | 0.2   | 6  | -  | μs   |  |
| tı                              | -   |  | 50   | ns   |  |
| t <sub>AA</sub>                 | -   |  | 0.45   | μs   |  |
| tBUF                            | 0.5   |  | -  | μs   |  |
| thd:sta                         | 0.26  |  | -  | μs   |  |
| tsu:sta                         | 0.2   | 6  | -  | μs   |  |
| thd:dat                         | 0   |  | -  | μs   |  |
| tsu:dat                         | 50  | )  | -  | ns   |  |
| t <sub>R</sub>                  | -   |  | -  | ns   |  |
| t⊧                              | -   |  | -  | ns   |  |
| tsu:sто                         | 0.2   | 6  | -  | μs   |  |
| t <sub>DH</sub>                 | 50  | )  | -  | ns   |  |
| twr                             | -   |  | 3  | ms   |  |
| Endurance                       | 1N  | 1  | -  | Write Cycle  |  |
|                                 | TA =-40°C to +125°C   Symbol   fscL   tLow   tLow   thigh   tLow   thigh   thigh   thigh   thigh   tsussta   thussta   thussta   tsusta   tsusta   tsusta   tsusta   thussta   tsusta   ts | fscl   -     tLow   0.5     tLow   0.2     tHIGH   0.2     tI   -     tAA   -     tBUF   0.5     tHD:STA   0.2     tHD:STA   0.2     tHD:STA   0.2     tHD:STA   0.2     tHD:DAT   0     tsu:DAT   50     tF   -     tsu:STO   0.2     tDH   50     tWR   -     Endurance   1M | $\begin{tabular}{ c c c c } \hline $T_A = -40^{\circ}C to +125^{\circ}C & $C_L = 1$ \\ \hline $Symbol $ $Min.$ \\ \hline $f_{SCL}$ $-$ \\ \hline $t_{LOW}$ $0.5 \\ \hline $t_{HIGH}$ $0.26 \\ \hline $t_{HIGH}$ $0.26 \\ \hline $t_{HIGH}$ $0.5 \\ \hline $t_{HD} STA $0.26 \\ \hline $t_{BUF}$ $0.26 \\ \hline $t_{BUF}$ $0.26 \\ \hline $t_{SU:STA}$ $0.26 \\ \hline $t_{SU:STA}$ $0.26 \\ \hline $t_{SU:DAT}$ $50 \\ \hline $t_{R}$ $-$ \\ \hline $t_{SU:DAT}$ $50 \\ \hline $t_{R}$ $-$ \\ \hline $t_{SU:STO}$ $0.26 \\ \hline $t_{DH}$ $50 \\ \hline $t_{WR}$ $-$ \\ \hline $t_{WR}$ $-$ \\ \hline $Endurance $1M$ \\ \hline \end{tabular}$ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ |  |

# Notes:

- 1. This parameter is ensured by characterization only.
- 2. There is no min. or max. values for the input signal rise and fall times. It is however recommended by the I<sup>2</sup>C specification that the input signal rise and fall times be less than 120 ns when  $f_{SCL} < 1$  MHz, more than 20 ns and less than 300 ns when  $f_{SCL} < 400$  kHz.
- 3. AC measurement conditions:

 $\begin{array}{l} \mathsf{R}_{\mathsf{L}} \text{ (connects to } \mathsf{V}_{\mathsf{CC}}\text{): } 1.3 \ \mathsf{k}\Omega \\ \\ \mathsf{Input} \text{ pulse voltages: } 0.3 \ \mathsf{V}_{\mathsf{CC}} \text{ to } 0.7 \ \mathsf{V}_{\mathsf{CC}} \\ \\ \\ \mathsf{Input} \text{ rise and fall time: } 50 \ \mathsf{ns} \\ \\ \\ \mathsf{Input} \text{ and output timing reference voltages: } 0.5 \ \mathsf{V}_{\mathsf{CC}} \\ \\ \\ \\ \mathsf{The value of } \mathsf{R}_{\mathsf{L}} \text{ should be concerned according to the actual loading on the user's system.} \end{array}$ 



# 24LC01/24AA01 Bus Timing

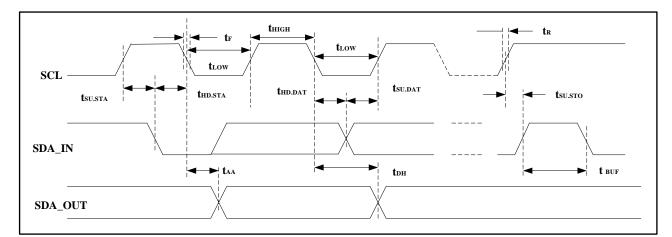


Figure 12. SCL: Serial Clock, SDA: Serial Data I/O

Write Cycle Timing

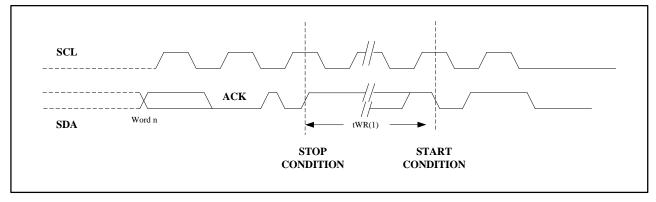
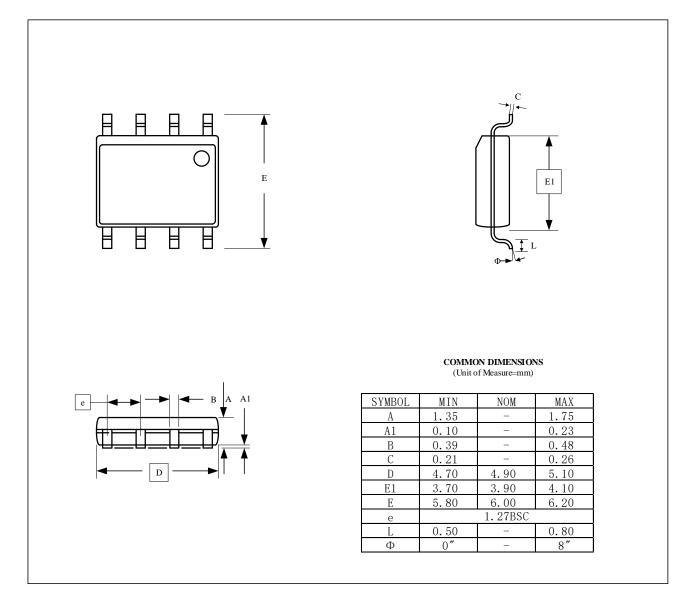


Figure 13. SCL: Serial Clock, SDA: Serial Data I/O

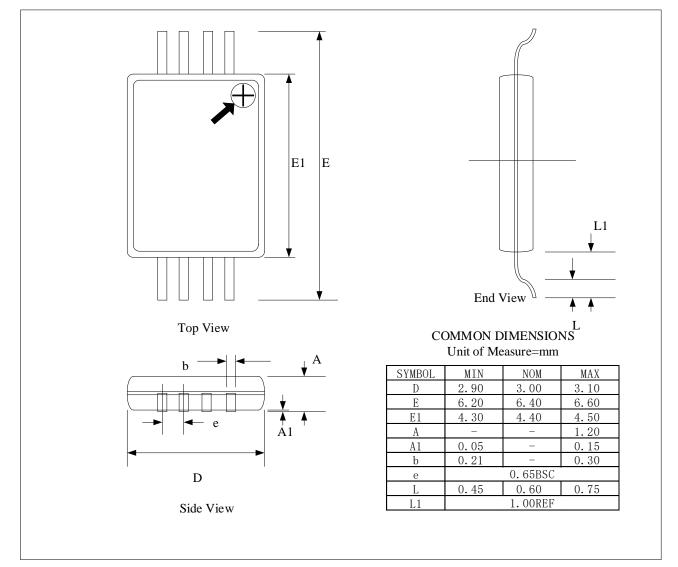
# 24LC01/24AA01 Package Information SOP







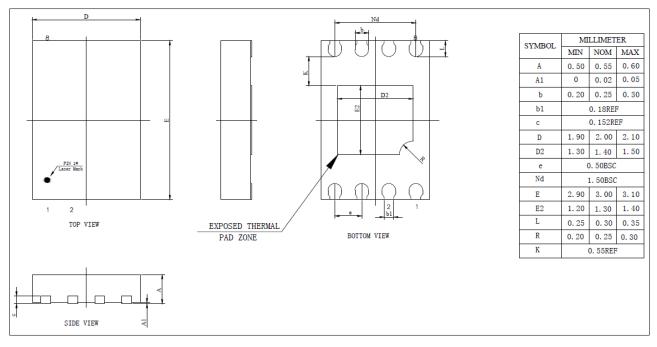
# TSSOP





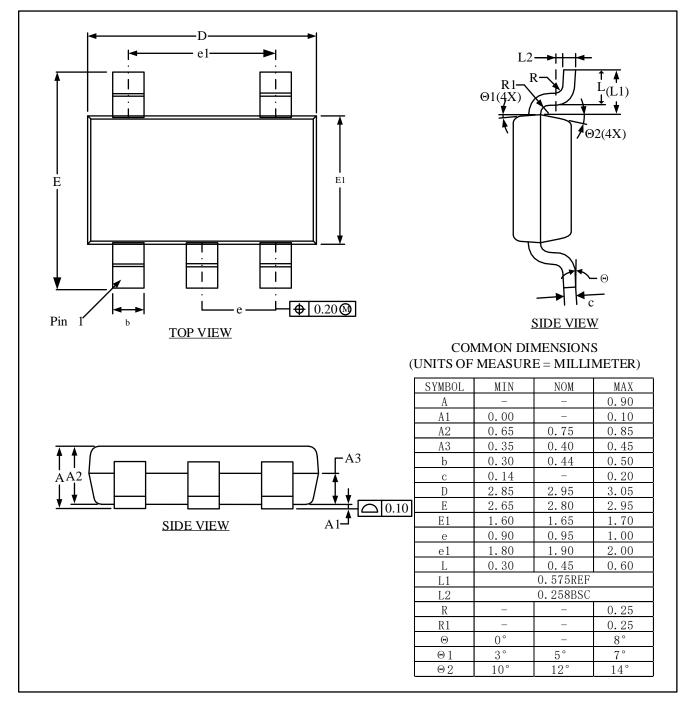


# UDFN



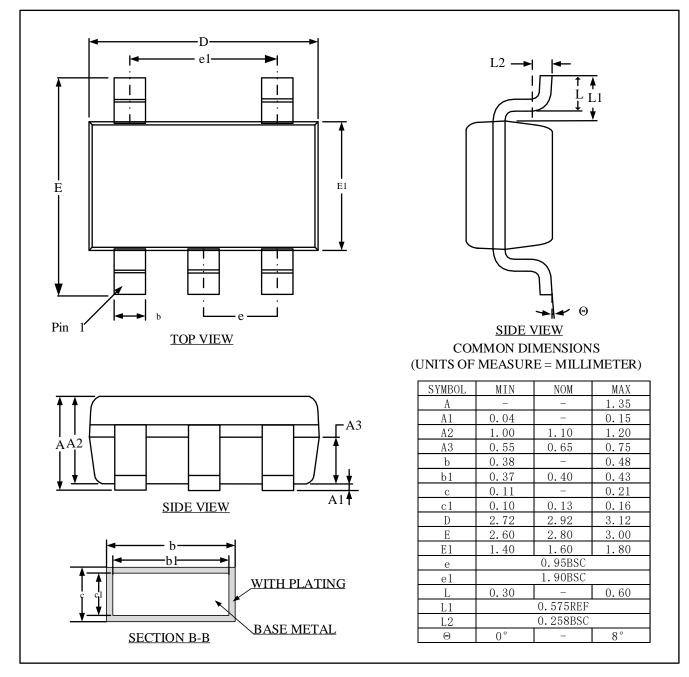
# 

# TSOT23-5





#### SOT23-5



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24LC01/24AA01 Revision

history



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