# Fluxgate system / Voltage-output type

# F01P SERIES







RoHS

TAMURA recommends F01P L series  $\,$  as a succession model.

# **ABSOLUTE MAXIMUM RATINGS**

Parameters	Symbol	Unit	Value	Comment
Supply voltage	Vcc	٧	7	
Primary conductor temperature	_	°C	110	
ESD(HBM: Human Body Model)	_	kV	4	C=100pF, R=1.5kΩ

# **ISOLATION CHARACTERISTICS**

100E (110II OIBII UIO IEIGO IIO				
Parameters	Symbol	Unit	Value	Comment
Insulation voltage	Vd	_	AC4200V, for 1minute(Sensing current 0.5mA)	Primary ⇔ Secondary
Insulation Resistance	R <sub>IS</sub>	_	≧ 500MΩ(at DC500V)	Primary ⇔ Secondary
Clearance distance	d <sub>Cl</sub>		7.7mm	Primary ⇔ Secondary
Creepage distance	d <sub>Cp</sub>		7,7mm	Primary ⇔ Secondary
Case material	_		UL94 V-0	
Comparative Tracking Index; (CTI)	CTI	٧	600	
Application example	_	(\$(	300V, GAT III, PD2	Reinforced isolation,non uniform field according to EN62477-1, EN61010
			600V, CAT Ⅲ, PD2	Simple isolation,non uniform field according to EN50178, EN61010

# ENVIRONMENTAL AND MECHANICAL CHARACTERISTICS

Parameters		Symbol	Unit	Value			Comment	
	^		-•	00	MIN	TYP	MAX	
Ambient operating temperature			T <sub>A</sub>	°C	-40		+105	
Ambient storage temperature			Ts	°C	-40		+105	
Mass	$\sim$	>	m	g		12		

SPECIFICATIONS

 $T_A$ =+25°C, Np=1T, RL=10k $\Omega$ , Vcc=+5V

Parameters		Symbol	Unit		Value		Comment
Farameters		Symbol	Unit	MIN TYP		MAX	
Primary nominal current	F01P006S05	$I_{PN}$	Α		6		
	F01P015S05				15		
	F01P025S05				25		
	F01P050S05				50		
Primary current, measuring range	F01P006S05	I <sub>PM</sub>	Α	-20		20	
	F01P015S05			<b>-51</b>		51	
	F01P025S05			-85		85	
	F01P050S05			-150		150	
Supply Voltage		Vcc	٧	4.75	5.00	5.25	
Number of primary turns		Np	Т		1, 2, 3		
Number of secondary turns	F01P006S05	Ns	Т		1816		
	F01P015S05				1737		
	F01P025S05				1764		
	F01P050S05				1600		
Consumption current (at I <sub>p</sub> )	F01P006S05	Icc	mA		25		Ico=15+Ip(mA) / Ns
	F01P015S05				30		
	F01P025S05				35		$\bigcirc \triangleright$
	F01P050S05				55		
Output voltage range		Vo	V	0.375		4.625	
Output voltage(at Ip=0A)		Vo	٧		2.5		
Electrical offset voltage *1	F01P006S05	Voe	mV	-10.40		10.40	
	F01P015S05			<del>-7.10</del>		7.10	
	F01P025S05		0.1	-6.25		6.25	
	F01P050S05		>>/	-5.80		5.80	
Electrical offset current referred to primary*1	F01P006S05	loe	/\X /	-0.10		0.10	
	F01P015S05			<b>−</b> 0.17		0.17	
	F01P025S05			-0.25		0.25	
	F01P050S05			-0.46		0.46	
Temperature coefficient of Vo(at Ip=0A)	F01P006S05	TCV₀	ppm/K		±10.0	±80.0	ppm/K of 2.5V
	F01P015S05	]			±7.5	±70.0	(−40°C <b>~</b> +105°C)
7/	F01P025S05	]			±6.5	±60.0	
	F01P050S05				±6.0	±60.0	
Theoretical sensitivity	F01P006S05	Gth	mV/A		104.2		625mV/I <sub>PN</sub>
\\ \( \( \) \\	F01P015S05				41.67		
	F01P025S05				25		
\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	F01P050S05				12.5		
Sensitivity error		ε <sub>G</sub>	%	-0.7		0.7	
Temperature coefficient of Sensitivity(at T <sub>A</sub> =-40°C~+105°C;	)	TCG	ppm/K			±40	
Linearity error(at I <sub>p</sub> )		٤١	%	-0.1		0.1	
Magnetic offset current referred to primary (at $10 \times Ip$ )		$I_{OM}$	Α	-0.1		0.1	

<sup>\*1</sup> Offset voltage value is after removal of core hysteresis.

SPECIFICATIONS

 $T_A$ =+25°C, Np=1T, RL=10k $\Omega$ , Vcc=+5V

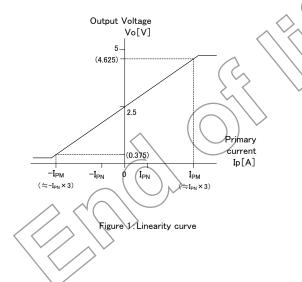
Parameters		Symbol	Unit	Value			Comment
				MIN	TYP	MAX	Comment
Peak to peak output ripple at oscillator freqency(f typ=450kHz)	F01P006S05	_	mV		40	160	RL=1kΩ
	F01P015S05				15	60	
	F01P025S05				10	40	
	F01P050S05				5	20	
Reaction time(at 10% of I <sub>PN</sub> )	F01P006S05	t <sub>ra</sub>	μs			0.3	RL=1k $\Omega$ , di/dt=18A/ $\mu$ s
	F01P015S05					0.3	RL=1k $\Omega$ , di/dt=44A/ $\mu$ s
	F01P025S05					0.3	RL=1k $\Omega$ , di/dt=68A/ $\mu$ s
	F01P050S05					0.3	RL=1k $\Omega$ , di/dt=100A/ $\mu$ s
Response time (at 90% of I <sub>PN</sub> )	F01P006S05	tr	μs			0.3	RL=1k $\Omega$ , di/dt=18A/ $\mu$ s
	F01P015S05					0.3	RL=1k $\Omega$ , di/dt=44A/ $\mu$ s
	F01P025S05					0.3	RL=1k $\Omega$ , di/dt=68A/ $\mu$ s
	F01P050S05					0.3	RL=1kΩ, di/dt=100A/μs
Frequency bandwidth(±1dB)		BW	kHz	200			RL=1kΩ
Frequency bandwidth(±3dB)		BW	kHz	300			RL=1kΩ
Overall Accuracy (at T <sub>A</sub> =25°C)	F01P006S05	$X_G$	%			2.5	$X_G$ =(100 × Voe/625)+ $\varepsilon$ <sub>G</sub> + $\varepsilon$ <sub>L</sub>
	F01P015S05					1.9	
	F01P025S05					1.8	
	F01P050S05					1.7	$\bigcup \mathcal{N}$

#### STANDARDS

EN50178, EN62477-1, EN61010-1, EN62368-1, UL508(file No.E243511)

XPlease refer to the another sheet about conditions of UL Recognition.

# Characteristic curve (TYP)



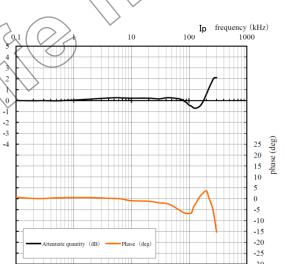


Figure 2:Frequency response curve ex) F01P025S05 Measurement condition Ta=+25°C, RL=1k $\Omega$ , Ip=3A, Vcc=+5V



#### SUPPORT DOCUMENTATION

#### Maximum continuous DC primary current

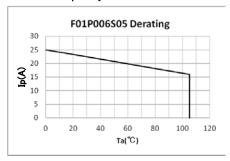


Figure 3:Ip vs Ta for F01P006S05

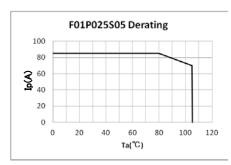


Figure 5:Ip vs Ta for F01P025S05

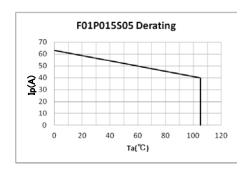


Figure 4: Ip vs Ta for F01P015S05

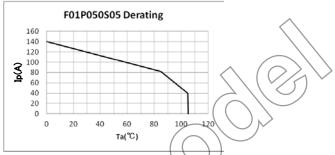


Figure 6:Ip vs Ta for F01P050S05

current plot shows the boundary of the area. According to which the following conditions are true the maximum continuous DC primary

- $\bigcirc$ Ip < Ipmax
- ②Junction temperature Tj < 125°C ③Resistor power dissipation < 0.5 x rated power

# Frequency derating

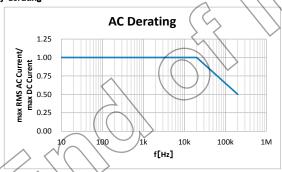
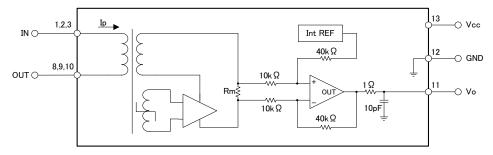


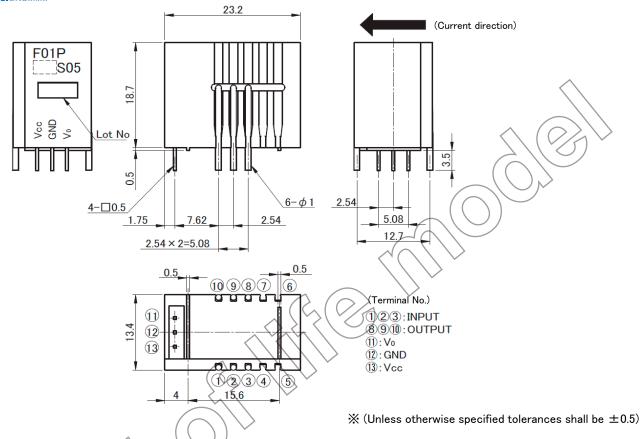
Figure 7: Maximum RMS AC primary current/maximum DC primary current vs frequency

# CONNECTION

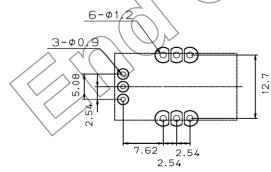


If/3	10 9 8 Q Q O OUT	
11, 0	IN O O O 1 2 3	
If/2	10 9 в оит	
	IN 0-0 0 1 2 3	
If	10 9 8 O—O—O OUT	
	IN O-O-O 1 2 3	

#### DIMENSIONS(mm)



# RECOMMENDED HOLE DIAMETER(rom)



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# **Application notes**

#### <General Considerations>

- 1. The sensor uses polar electronic components. When the polarity of the power supply is mistaken, the sensor is damaged.
- 2. Static electricity or excessive voltage can increase an offset voltage in the Hall element, and cause offset voltage to change. Please exercise care in handling and application.
- 3. In order to prevent the influence of noise, the use of twisted cable or shielded cable for the output line is recommended
- 4. If using this device within a magnetic field generated by other devices, the specified accuracy may not be obtainable.
- 5. Our products (several models are excluded ) are adjusted with the trimming method by the measurement condition (Load resistance, Power supply voltage) of specification sheets. Therefore, characteristics (Offset, Output, etc.) and its deviation may be changed in different circuit conditions from the measurement condition. All change characteristic items are not indicated on specification sheets.
- 6. The performance of current sensors with through-hole (aperture) is dependent on the position of the primary conductor. Tamura specifications are based on a primary conductor completely filling the through-hole (aperture) area.
- 7. The current sensor rated current in DC Amps.
- 8. Please use mating connector with equivalent terminal plating material to insure proper operation and avoid possibility of 'galvanic corrosion'.
- 9. Please do not store in high-temperature and high-humidity storage environment. Please use it after confirming soldering when it is kept for six months or more. (product soldered with substrate)
- 10. We recommend performing a zero offset adjustment by measuring the offset voltage at startup. In continuously operation for a few months, or at change of ambient temperature or humidity is large, we recommend regularly performing a zero offset adjustment at being idling (it is clear that the current is not apply) .
- 11. The current sensor doesn't have built-in protection circuit (devices and fuses, etc.). As a failure mode of the sensor, there is a short circuit and open state. In the case of a shortcircuit state, the abnor-mal temperature rise of the internal parts is assumed, and there is a possibility to smoke and to ignite. If it is used in safety critical circuit blocks, please take appropriate measures by protection devices, protection circuits, etc. For closed loop -type sensors and flux gate (closed loop type) sensors, the consumption current of the secondary power supply varies in proportion to the measurement current.

#### <Open loop>

- 1. High frequency primary current may result in excessive heating in iron magnetic core and cause damage to internal circuitry; for high frequency applications select current sensor with ferrite core material.
- 2. If the measured current exceeds the rated current, magnetic core saturation will occur and the output voltage signal will not be linearly proportional to the measured current.

#### <Closed Loop>

- 1. For closed loop current sensors please insure the power supply voltage is balanced, symmetrical, and, applied simultaneously to avoid potential increase in DC offset error.
- 2. Maximum rated current measurement duration is timedependent. Maximum rated current applied in excess of the time limit can result in damage to internal electronic circuitry; please consult Tamura for assistance.
- 3. When using a measurement resistor to convert current output to voltage output select a resistor with stable temperature characteristic to insure accuracy of the output voltage.
- 4. Compensation current supplied to the secondary winding varies in proportion to the measured current based on the conversion ratio. (If/KN; KN = secondary turns) Please insure the PSU has required current capacity to supply compensation current to the secondary winding.

#### <Flux-Gate>

- 1. Compensation current supplied to the secondary winding varies in proportion to the measured current. Please insure the PSU has required current capacity to supply compensation current to the secondary winding.
- 2. There is 450kHz ripple voltage present on the output and reference output voltage signals . An external capacitor maybe added if necessary.